

# Dynamical Systems and Chaos 2015 Spring

Homework Solutions, Session 10

March 9, 2015

## 9 Lorenz Equations

### 9.1 A Chaotic Waterwheel

#### 9.1.4

(a)  $\dot{P} = 0$  gives  $ED = P$  and  $\dot{D} = 0$  gives  $D = \lambda + 1 - \lambda EP$ . Therefore

$$P = \frac{(\lambda + 1)E}{\lambda E^2 + 1}$$

and

$$\dot{E} = \kappa \left( \frac{(\lambda + 1)E}{\lambda E^2 + 1} - E \right)$$

Denote the terms on the right hand side as  $f(E)$ , and

$$f'(E) = \kappa \left[ \frac{(\lambda + 1)(1 - \lambda E^2)}{(\lambda E^2 + 1)^2} - 1 \right]$$

- If  $\lambda < 0$ , there are 3 fix points  $E_1^* = 0$ ,  $E_2^* = 1$  and  $E_3^* = -1$ . The derivate at  $E_1^* = 0$  is  $f'(E_1^*) = \lambda\kappa < 0$ , so it is stable.
- If  $\lambda = 0$ , there are infinite fix points. The derivative at  $E^* = 0$  is  $f'(E^*) = 0$ , showing that  $\lambda = 0$  is the bifurcation point.
- If  $\lambda > 0$ , there are 3 fix points  $E_1^* = 0$ ,  $E_2^* = 1$  and  $E_3^* = -1$ . The derivate at  $E_1^* = 0$  is  $f'(E_1^*) = \lambda\kappa > 0$ , so it is unstable.

Therefore, it is a degenerate pitchfork bifurcation.

(b) By comparing the equation of  $\dot{\tilde{x}}$  and  $\dot{E}$ , we have  $\tilde{t} = \kappa t / \sigma$ ,  $\tilde{x} = \alpha E$  and  $\tilde{y} = \alpha P$  where  $\alpha$  needs to be determined. For verification of such transformation, we have

$$\frac{d\tilde{x}}{d\tilde{t}} = \frac{\alpha dE}{\kappa / \sigma dt} = \frac{\alpha \sigma}{\kappa} \frac{dE}{dt} = \alpha \sigma (P - E) = \sigma (\tilde{y} - \tilde{x})$$

Then we compute  $d\tilde{y}/d\tilde{t}$  with  $\dot{P}$  to obtain the transformation of  $\gamma_1$  and  $D$ .

$$\frac{d\tilde{y}}{d\tilde{t}} = \frac{\alpha \sigma dP}{\kappa dt} = \frac{\alpha \sigma}{\kappa} \gamma_1 (ED - P) = \frac{\sigma}{\kappa} \gamma_1 (\tilde{x}D - \tilde{y}) = \tilde{x}(r - \tilde{z}) - \tilde{y}$$

Therefore  $\gamma_1 = \kappa/\sigma$  and  $D = r - \tilde{z}$ .

Finally compute  $d\tilde{z}/dt$  with  $\dot{E}$  to determine the transformation of the remaining variables.

$$\frac{d\tilde{z}}{dt} = -\frac{dD}{\kappa/\sigma dt} = -\frac{\sigma dD}{\kappa dt} = -\frac{\sigma\gamma_2}{\kappa}(\lambda+1-D-\lambda EP) = -\frac{\sigma\gamma_2}{\kappa}(\lambda+1-r) - \frac{\sigma\gamma_2}{\kappa}\tilde{z} + \frac{\sigma\gamma_2}{\kappa}\alpha^2\lambda\tilde{x}\tilde{y} = \tilde{x}\tilde{y} - b\tilde{z}$$

Therefore  $\lambda = r - 1$ ,  $\gamma_2 = b\kappa/\sigma$  with a special relationship  $\alpha = [b(r - 1)]^{-1/2}$ .

## 9.2 Simple Properties of the Lorenz Equations

### 9.2.1

(a) The two fix points are  $(x^*, y^*, z^*) = (\pm\sqrt{b(r-1)}, \pm\sqrt{b(r-1)}, r-1)$ , if  $r > 1$ , and the Jacobian is

$$\mathbf{J}|_{(x^*, y^*, z^*)} = \begin{bmatrix} -\sigma & \sigma & 0 \\ r-z & -1 & -x \\ y & x & -b \end{bmatrix} \Big|_{(x^*, y^*, z^*)} = \begin{bmatrix} -\sigma & \sigma & 0 \\ 1 & -1 & \mp\sqrt{b(r-1)} \\ \pm\sqrt{b(r-1)} & \pm\sqrt{b(r-1)} & -b \end{bmatrix}$$

The characteristic polynomial is

$$\begin{aligned} P(\lambda) &= |\lambda\mathbf{I} - \mathbf{J}| = \det \begin{bmatrix} \lambda + \sigma & -\sigma & 0 \\ -1 & \lambda + 1 & \pm\sqrt{b(r-1)} \\ \mp\sqrt{b(r-1)} & \mp\sqrt{b(r-1)} & \lambda + b \end{bmatrix} \\ &= (\lambda + \sigma)(\lambda + 1)(\lambda + b) + \sigma b(r-1) - \sigma(\lambda + b) + (\lambda + \sigma)b(r-1) \\ &= \lambda^3 + (\sigma + b + 1)\lambda^2 + b(\sigma + r)\lambda + 2\sigma b(r-1) = 0 \end{aligned}$$

(b) Denote the solutions of  $P(\lambda) = 0$  as  $\lambda_{1,2,3}$  and we have

$$\lambda_1 + \lambda_2 + \lambda_3 = -(\sigma + b + 1), \lambda_1\lambda_2 + \lambda_1\lambda_3 + \lambda_2\lambda_3 = b(\sigma + r), \lambda_1\lambda_2\lambda_3 = -2\sigma b(r-1)$$

Assume  $\lambda_1 = \omega i$  and  $\lambda_2 = -\omega i$  where  $\omega \in \mathbb{R}$ , and the first equation gives  $\lambda_3 = -(\sigma + b + 1)$  and the second equation gives  $\omega = \sqrt{b(\sigma + r)}$ . Solving the third equation gives that

$$-(\sigma + b + 1)b(\sigma + r) = -2\sigma b(r-1) \rightarrow r = \frac{(\sigma + b + 1)b\sigma + 2\sigma b}{2\sigma b - (\sigma + b + 1)b} = \sigma \frac{\sigma + b + 3}{\sigma - b - 1}$$

Since  $r_H > 0$  and  $\sigma, b > 0$ , we should have  $\sigma > b + 1$ .

(c)  $\lambda_3 = -(\sigma + b + 1)$ .

### 9.2.6

(a) The divergence of the vector field is

$$\begin{aligned} \nabla \cdot \vec{f} &= \frac{\partial f_1}{\partial x} + \frac{\partial f_2}{\partial y} + \frac{\partial f_3}{\partial z} \\ &= -v - v + 0 = -2v \end{aligned}$$

Therefore the volume  $V$  follows the relationship that  $\dot{V} = -2vV$  and  $V = V(0)e^{-2vt}$ .  $V$  is decreasing, so the system is dissipative.

(b) Note that  $x^* = \pm k$  and  $y^* = \pm k^{-1}$ , obviously  $x^*y^* = (\pm k)(\pm k^{-1}) = 1$  and  $\dot{z} = 0$  is satisfied.

Since  $z = vk^2$ , we have  $zy - vx = (vk^2)(\pm k^{-1}) - v(\pm k) = (\pm vk) - (\pm vk) = 0$  and  $\dot{x} = 0$  is satisfied.

Finally by setting  $\dot{y} = 0$ , we have

$$vy = (z - a)x \rightarrow \pm vk^{-1} = \pm(vk^2 - a)k \rightarrow vk^{-1} = (vk^2 - a)k \rightarrow vk^{-2} = vk^2 - a \rightarrow v(k^2 - k^{-2}) = a$$

(c) Without loss of generality, the Jacobian at the fix point  $(k, k^{-1}, vk^2)$  is

$$\mathbf{J}|_{(k, k^{-1}, vk^2)} = \begin{bmatrix} -v & z & y \\ z - a & -v & x \\ -y & -x & 0 \end{bmatrix} \Big|_{(k, k^{-1}, vk^2)} = \begin{bmatrix} -v & vk^2 & k^{-1} \\ vk^2 - a & -v & k \\ -k^{-1} & -k & 0 \end{bmatrix}$$

so the eigenvalues of the Jacobian follows

$$0 = \det(\mathbf{J}|_{(k, k^{-1}, vk^2)} - \lambda \mathbf{I}) = \det \begin{bmatrix} -v - \lambda & vk^2 & k^{-1} \\ vk^2 - a & -v - \lambda & k \\ -k^{-1} & -k & -\lambda \end{bmatrix}$$

and we have

$$\lambda^3 + 2v\lambda^2 + (k^2 + k^{-2})\lambda + 2v(k^2 + k^{-2}) = 0$$

Since  $v, k^2 > 0$ , we have

$$\lambda_1 + \lambda_2 + \lambda_3 = -2v < 0; \lambda_1\lambda_2 + \lambda_2\lambda_3 + \lambda_3\lambda_1 = k^2 + k^{-2} > 0 \text{ and } \lambda_1\lambda_2\lambda_3 = -2v(k^2 + k^{-2}) < 0$$

The third relation only yields two possible cases: (1)  $\lambda_1 < 0, \lambda_{2,3} > 0$  and (2)  $\lambda_{1,2,3} < 0$ . However, for case (1), we have

$$\lambda_1\lambda_2 + \lambda_2\lambda_3 + \lambda_3\lambda_1 = \lambda_1(\lambda_2 + \lambda_3) + \lambda_2\lambda_3 < -(\lambda_2 + \lambda_3)^2 + \lambda_2\lambda_3 = -\lambda_2^2 - \lambda_2\lambda_3 - \lambda_3^2 < 0$$

contradicting to the second relation. Therefore, all three eigenvalues are negative and the fix point is stable.

## 9.4 Lorenz Map

### 9.4.2

(a)  $f(x)$  looks like a tent.

(b)

- If  $0 \leq x^* \leq 1/2$ , solving  $f(x^*) = x^*$  gives  $x^* = 0$ . It is unstable since  $f'(x^*) = 2 > 1$ .
- If  $1/2 < x^* \leq 1$ , solving  $f(x^*) = x^*$  gives  $x^* = 2/3$ . It is unstable since  $f'(x^*) = -2 < -1$ .

(c)

- If  $0 \leq x^* \leq 1/2$  and  $0 \leq f(x^*) \leq 1/2$ ,  $f(f(x^*)) = f(2x^*) = 4x^* = x^*$ . So  $x^* = 0$  and it is not a period-2 orbit.

- If  $0 \leq x^* \leq 1/2$  and  $1/2 < f(x^*) \leq 1$  (and same for  $1/2 < x^* \leq 1$  and  $0 \leq f(x^*) \leq 1/2$ ),  $f(f(x^*)) = f(2x^*) = 2 - 4x^* = x^*$ . So  $x^* = 2/5$ ,  $f(x^*) = 4/5$  and it is unstable.
- If  $1/2 < x^* \leq 1$  and  $1/2 < f(x^*) \leq 1$ ,  $f(f(x^*)) = f(2 - 2x^*) = 4x^* - 2 = x^*$ . So  $x^* = 2/3$  and it is not a period-2 orbit.

(d) Period-3. For simplicity, here describe the relationship between  $x^*$ ,  $f(x^*)$ ,  $f(f(x^*))$  and  $1/2$ , respectively.

- $<, <, <$ :  $f(f(f(x^*))) = f(f(2x^*)) = f(4x^*) = 8x^* = x^*$ . So  $x^* = 0$  and it is not a period-3 orbit.
- $<, <, >$  (same for  $<, >, <$  and  $>, <, <$ ):  $f(f(f(x^*))) = f(4x^*) = 2 - 8x^* = x^*$ . So  $x^* = 2/9$ ,  $f(x^*) = 4/9$ ,  $f(f(x^*)) = 8/9$ . It is unstable.
- $<, >, >$  (same for  $>, <, >$  and  $>, >, <$ ):  $f(f(f(x^*))) = f(f(2x^*)) = f(2 - 4x^*) = 8x^* - 2 = x^*$ . So  $x^* = 2/7$ ,  $f(x^*) = 4/7$ ,  $f(f(x^*)) = 6/7$  and it is unstable.
- $>, >, >$ :  $f(f(f(x^*))) = f(f(2 - 2x^*)) = f(4x^* - 2) = 6 - 8x^* = x^*$ . So  $x^* = 2/3$  and it is not a period-3 orbit.

Period-4.

- $<, <, <, <$ :  $f(f(f(f(x^*)))) = 16x^* = x^*$ , so  $x^* = 0$  and it is not a period-4 orbit.
- $<, <, <, >$  (and 3 others):  $f(f(f(f(x^*)))) = f(8x^*) = 2 - 16x^* = x^*$ . So  $x^* = 2/17$ ,  $f(x^*) = 4/17$ ,  $f(f(x^*)) = 8/17$ ,  $f(f(f(x^*))) = 16/17$ . It is unstable.
- $<, <, >, >$  (and 3 others):  $f(f(f(f(x^*)))) = f(f(4x^*)) = f(2 - 8x^*) = 16x^* - 2 = x^*$ . So  $x^* = 2/15$ ,  $f(x^*) = 4/15$ ,  $f(f(x^*)) = 8/15$ ,  $f(f(f(x^*))) = 14/15$ . It is unstable.
- $<, >, <, >$  (and 1 other):  $f(f(f(f(x^*)))) = f(f(2 - 4x^*)) = 16x^* - 6 = x^*$ . So  $x^* = 2/5$ ,  $f(x^*) = 4/5$  and it is not a period-4 orbit.
- $<, >, >, >$  (and 3 others):  $f(f(f(f(x^*)))) = f(f(f(2x^*))) = f(f(2 - 4x^*)) = f(8x^* - 2) = 6 - 16x^* = x^*$ . So  $x^* = 6/17$ ,  $f(x^*) = 12/17$ ,  $f(f(x^*)) = 10/17$ ,  $f(f(f(x^*))) = 14/17$ . It is unstable.
- $>, >, >, >$ :  $f(f(f(f(x^*)))) = f(f(f(2 - 2x^*))) = f(f(4x^* - 2)) = f(6 - 8x^*) = 16x^* - 10 = x^*$ . So  $x^* = 2/3$  and it is not a period-4 orbit.