Flows on the Line

2.4 Linear Stability Analysis

Let's consider the non-linear first-order equation

$$\frac{dx}{dt} = f(x) \tag{1}$$

with x^* a fixed point of f(x). Then, if η is a small perturbation, such that $x = x^* + \eta$, the Taylor expansion (to second order) of Eq. 1 reads

$$\frac{d(x^* + \eta)}{dt} = \frac{d\eta}{dt} = f(x^*) + f'(x^*)\eta + \frac{1}{2}f''(x^*)\eta^2 + O(\eta^3).$$
(2)

Because $f(x^*) = 0$ we have

$$\dot{\eta} \simeq f'(x^*)\eta + \frac{1}{2}f''(x^*)\eta^2.$$
 (3)

We now find the solution of equation Eq. (3) neglecting the quadratic term in η , thus

$$\int \frac{d\eta}{\eta} = \int f'(x^*)dt + c \qquad (4)$$
$$\eta = c_1 e^{f'(x^*)t}$$

Eq. (4) says that any perturbation close a fixed point will decay or grow exponentially, depending on the sign of $f'(x^*)$. A stable solution will always decay to the fixed point, i.e. $f'(x^*) < 0$. If $f'(x^*) = 0$, Eq. (4) is non longer valid to assess the stability of the point x^* and we need to consider higher orders of the Taylor expansion, that is $\sim f^n(x^*)\eta^n$, with $f^n(x^*) \neq 0$.

2.4.1 $\dot{x} = x(1-x)$

Fixed points are x = 0 and x = 1 and

$$f'(x) = 1 - 2x, (5)$$

then, because f'(0) > 0 and f'(1) < 0, x = 0 is unstable and x = 1 is stable.

2.4.4
$$\dot{x} = x^2(6-x)$$

Fixed points are x = 0 and x = 6, and

$$f'(x) = 12x - 3x^2, (6)$$

then, because f'(0) = 0 and f'(6) < 0, it follows that x = 6 is stable, but we need to use more information to study the stability of x = 0, in this case we will use a graphical argument. From Figure 1 we conclude that x = 0 is a half-stable fixed point.



Figure 1: Stability of x = 0 for $\dot{x} = x^2(6 - x)$.

2.4.7 $\dot{x} = ax - x^3$

Fixed points depend on the value of a.

- Case (a): a > 0
- Case (b): a < 0
- Case (c): a = 0

with

$$f'(x) = a - 3x^2,$$
 (7)

Case (a):

Fixed points are x = 0 and $x = \pm \sqrt{a}$. Because f'(0) > 0 and $f'(\pm \sqrt{a}) < 0$, x = 0 is unstable and $x = \pm \sqrt{a}$ are stable.

Case (b):

Fixed point x = 0 ($x = \pm \sqrt{a}$ are imaginary roots). In this case f'(0) < 0 and x = 0 is stable. Case (c):

Fixed point x = 0. In this case f'(0) = 0, so we use a graphical argument to study the stability of x = 0. From Figure 2 we conclude that x = 0 is a stable fixed point.

2.5 Existence and Uniqueness

2.5.3 $\dot{x} = rx + x^3$

In this case, $f(x) = rx + x^3$ and $f'(x) = r + 3x^2$ are continuous in \mathbb{R} for all r in \mathbb{R} . Therefore, the solution exist and is unique for any initial condition x_0 .



Figure 2: Stability of x = 0 for $\dot{x} = -x^3$.

Analytical solution x(t), with $x(0) = x_0 \neq 0$ and r > 0:

$$\frac{dx}{x(r+x^2)} = dt$$

$$\int \frac{dx}{x(r+x^2)} = \int dt + c$$

$$-\frac{1}{2} \ln|r+x^2| + \ln|x| = rt + c_1$$

$$\frac{x}{\sqrt{r+x^2}} = e^{c_1}e^{rt}$$

$$\frac{x^2}{r+x^2} = c_2e^{2rt}$$

$$x(t) = \pm \sqrt{\frac{rc_2e^{r2t}}{1-c_2e^{2rt}}}$$
(8)

with $c_2 = x_0^2/(r + x_0^2)$. Then, the solution $x(t) \to \pm \infty$ when $1 - x_0^2/(r + x_0^2)e^{2rt} = 0$, this happen for $t = \ln\left(\frac{x_0^2 + r}{x_0^2}\right)\frac{1}{2r}$.

2.5.4 $\dot{x} = x^{1/3}$ has infinite solutions

In this case, $f(x) = x^{1/3}$ is continuous and $f'(x) = \frac{1}{3}x^{-2/3}$ is discontinuous at x = 0. Because f is continuous, the solution exist, but we can not ensure that the solution is unique. Analytical solution x(t) with x(0) = 0:

$$\frac{dx}{x^{1/3}} = dt$$

$$\int \frac{dx}{x^{1/3}} = \int dt + c$$

$$\frac{3}{2}x^{2/3} = t + c$$

$$x = \pm \left[\frac{2}{3}(t+c)\right]^{3/2}$$
(9)

The initial condition is satisfied if c = 0, so $x(t) = \left(\frac{2}{3}t\right)^{3/2}$, with $t \ge 0$. On the other hand, the function $x = -\left(\frac{2}{3}t\right)^{3/2}$ is also a solution of the initial value problem. Moreover, the function x = 0 for $t \ge 0$ is yet another solution.

Finally, we can construct a family of solutions, for any arbitrary positive t_0 , of the form:

$$x(t) = \begin{cases} 0, & \text{if } 0 \le t < t_0 \\ \pm [\frac{2}{3}(t - t_0)]^{3/2}, & \text{if } t \ge t_0 \end{cases}$$

which are continuous and differentiable (in particular in $t = t_0$).

2.6 Impossibility of the Oscillations

2.6.2

Let's consider the first order initial value problem defined by $\dot{x} = f(x)$, with f a continuous function in [x(t+T), x(t)]. Let's assume that x is a periodic function of t, such that x(t+T) = x(t), with T > 0. We want to prove that the only possible periodic function x(t), that is solution of $\dot{x} = f(x)$, is the constant function.

First, we have that the integral

$$\int_{t}^{t+T} f(x) \frac{dx}{dt} dt = \int_{t}^{t+T} \left(\frac{dx}{dt}\right)^{2} dt \ge 0,$$
(10)

which can be proven using the Cauchy-Schwarz Inequality

$$\left[\int_{a}^{b} h(t)g(t)dt\right]^{2} \leq \int_{a}^{b} h(t)^{2}dx \int_{a}^{b} g(t)^{2}dt$$
(11)

taking h(t) = dx/dt, g(t) = 1, a = t and b = t + T. Because x is periodic in [t, t+T] it follows that dx/dt is periodic in [t, t+T], and furthermore $0 \le [\int_t^{t+T} \frac{dx}{dt} dt]^2 = [\int_a^b h(t)g(t)dt]^2$. Thus, Eq. (11) transforms in

$$0 \le \int_{a}^{b} h(t)^{2} dx \int_{a}^{b} g(t)^{2} dt = (b-a) \int_{a}^{b} h(t)^{2} dx$$
(12)

where we used that $\int_a^b g(t)^2 dt = \int_a^b 1 dt = b - a = T$. Going back to the integral of Eq. (10)

$$\int_{t}^{t+T} f(x) \frac{dx}{dt} dt = \int_{x(t)}^{x(t+T)} f(x) dx = 0,$$
(13)

because x(t) = x(t+T).

Finally, we have that

$$0 = \int_{x(t)}^{x(t+T)} f(x)dx = \int_{t}^{t+T} f(x)\frac{dx}{dt}dt = \int_{t}^{t+T} \left(\frac{dx}{dt}\right)^{2} dt \ge 0$$
(14)

which will be only valid when $\int_{t}^{t+T} \left(\frac{dx}{dt}\right)^2 dt = 0$ if and only if dx/dt = 0, and thus x is necessarily a constant function of t.

2.7 Potentials

2.7.6

The potential, V, satisfies

$$-\frac{dV}{dx} = r + x - x^3,\tag{15}$$

integrating this equations, and furthermore assuming the constant of integration c = 0, we obtain

$$V(x) = -rx - \frac{1}{2}x^2 + \frac{1}{4}x^4$$
(16)

The fixed points are the solution of $0 = r + x - x^3$, which depends on the value of r. The discriminant of this cubic equation is $\Delta = r^2/4 - 1/27$, the we have two cases:

- $\Delta < 0$: 3 fixed points.
- $\Delta \ge 0$: 1 fixed point.



Figure 3: Case $\Delta < 0$ with r = 1/4. Left panel: Potential V(x). Right panel: \dot{x} . The locals minimum of the potential correspond to the stable fixed points, while the local maximum corresponds to the unstable fixed point.



Figure 4: Case $\Delta > 0$ with r = 1. Left panel: Potential V(x). Right panel: \dot{x} . The locals minimum of the potential correspond to the stable fixed points, while the local maximum corresponds to the unstable fixed point.